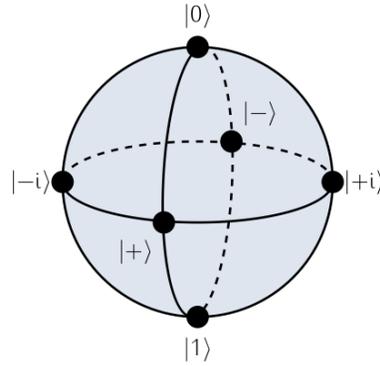
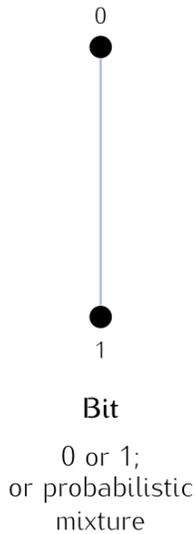


# ① Quantum States



$$|\psi\rangle = \alpha|0\rangle + \beta|1\rangle,$$

$$\alpha, \beta \in \mathbb{C},$$

$$|\alpha|^2 + |\beta|^2 = 1$$

$$|\pm\rangle = \frac{1}{\sqrt{2}}(|0\rangle \pm |1\rangle)$$

$$|\pm i\rangle = \frac{1}{\sqrt{2}}(|0\rangle \pm i|1\rangle)$$

Qubit  
 $|0\rangle$  or  $|1\rangle$ ;  
or *superposition*

\* States of live on the surface of the Bloch sphere. — they are described by 2-dimensional state vectors.

$$\{|k\rangle\}_{k=0}^{d-1} \quad \{|e_k\rangle\}_{k=1}^d$$

$$|\psi\rangle = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}, \quad \alpha, \beta \in \mathbb{C}, \quad |\alpha|^2 + |\beta|^2 = 1. \quad |\psi\rangle = \alpha|0\rangle + \beta|1\rangle, \quad |0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

(States inside the sphere are also possible — they are described by density matrices. We will see this today!)

## ② Matrices (aka "linear operators")

$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad |0\rangle\langle 0| = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad a, b, c, d \in \mathbb{C}.$$

row indices

column indices

$$M = a|0\rangle\langle 0| + b|0\rangle\langle 1| + c|1\rangle\langle 0| + d|1\rangle\langle 1|$$

$$a = \langle 0|M|0\rangle, \quad b = \langle 0|M|1\rangle, \quad c = \langle 1|M|0\rangle,$$

$$d = \langle 1|M|1\rangle.$$

- General dxd matrix:  $M = \sum_{i,j=0}^{d-1} m_{ij} |i\rangle\langle j|$ ,  $m_{ij} = \langle i|M|j\rangle$

matrix elements.

⊛ Notation:  $L(\mathbb{C}^d) \equiv$  set of all matrices/linear operators acting on  $\mathbb{C}^d$  (i.e.,  $d \times d$  matrices) (dimension is  $d^2$ .)

- For any vector  $|v\rangle \in \mathbb{C}^d$ ,  $|v\rangle\langle v| \in L(\mathbb{C}^d)$  is a  $d \times d$  matrix.

$$|v\rangle = \sum_{k=0}^{d-1} v_k |k\rangle \Rightarrow |v\rangle\langle v| = \left( \sum_{k=0}^{d-1} v_k |k\rangle \right) \left( \sum_{k'=0}^{d-1} \bar{v}_{k'} \langle k'| \right) = \sum_{k,k'=0}^{d-1} v_k \bar{v}_{k'} |k\rangle\langle k'|.$$

- Identity matrix:  $\mathbb{1} \rightarrow \mathbb{1}|v\rangle = |v\rangle$  for all  $|v\rangle \in \mathbb{C}^d$ .

$$\mathbb{1} = \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix} = \sum_{k=0}^{d-1} |k\rangle\langle k| \xrightarrow{M_{ij} = \delta_{ij}} \text{For any orthonormal basis } \{|e_k\rangle\}_{k=1}^d : \mathbb{1} = \sum_{k=1}^d |e_k\rangle\langle e_k|.$$

- Trace of a Matrix: Sum of the diagonal elements.

$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow \text{Tr}[M] = a + d = \langle 0|M|0\rangle + \langle 1|M|1\rangle.$$

$$\text{In general: } M = \sum_{i,j=0}^{d-1} M_{ij} |i\rangle\langle j| \Rightarrow \text{Tr}[M] = \sum_{i=0}^{d-1} M_{i,i} = \sum_{i=0}^{d-1} \langle i|M|i\rangle.$$

⊛ Consider a state vector  $|v\rangle = \alpha|0\rangle + \beta|1\rangle \Rightarrow \langle v| = \bar{\alpha}\langle 0| + \bar{\beta}\langle 1|$ ,  $|\alpha|^2 + |\beta|^2 = 1$ .

$$\Rightarrow |v\rangle\langle v| = (\alpha|0\rangle + \beta|1\rangle)(\bar{\alpha}\langle 0| + \bar{\beta}\langle 1|) = \alpha\bar{\alpha}|0\rangle\langle 0| + \alpha\bar{\beta}|0\rangle\langle 1| + \beta\bar{\alpha}|1\rangle\langle 0| + \beta\bar{\beta}|1\rangle\langle 1|$$

$$= |\alpha|^2 |0\rangle\langle 0| + \alpha\bar{\beta} |0\rangle\langle 1| + \beta\bar{\alpha} |1\rangle\langle 0| + |\beta|^2 |1\rangle\langle 1| = \begin{pmatrix} |\alpha|^2 & \alpha\bar{\beta} \\ \beta\bar{\alpha} & |\beta|^2 \end{pmatrix}$$

Now take the trace:  $\text{Tr}(|v\rangle\langle v|) = |\alpha|^2 + |\beta|^2 = 1$ .

$$\begin{aligned} |\alpha|^2 &= P_r[0] \\ |\beta|^2 &= P_r[1] \end{aligned}$$

In general:  $\text{Tr}(|v\rangle\langle v|) = \langle v|v\rangle$  for all  $|v\rangle \in \mathbb{C}^d$ .

Proof: Just use the definition!

$$\text{Tr}(|v\rangle\langle v|) = \sum_{k=0}^{d-1} \langle k|v\rangle\langle v|k\rangle = \sum_{k=0}^{d-1} \langle v|k\rangle\langle k|v\rangle = \langle v|\underbrace{\left(\sum_{k=0}^{d-1} |k\rangle\langle k|\right)}_{=I}|v\rangle = \langle v|I|v\rangle = \langle v|v\rangle.$$

Similarly:  $\text{Tr}(M|v_1\rangle\langle v_2|) = \langle v_2|M|v_1\rangle$  for all  $|v_1\rangle, |v_2\rangle \in \mathbb{C}^d$ ,  $M \in L(\mathbb{C}^d)$ .

Proof:  $\text{Tr}(M|v_1\rangle\langle v_2|) = \sum_{k=0}^{d-1} \langle k|M|v_1\rangle\langle v_2|k\rangle = \sum_{k=0}^{d-1} \langle v_2|k\rangle\langle k|M|v_1\rangle = \langle v_2|\underbrace{\left(\sum_{k=0}^{d-1} |k\rangle\langle k|\right)}_{=I}M|v_1\rangle$

$$= \langle v_2|M|v_1\rangle = \langle v_2|I \cdot M|v_1\rangle$$

$I|v\rangle = |v\rangle, I \cdot M = M$

- Transpose of a matrix: flip the rows and columns.

$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightarrow M^T = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$$

\* Note:  $(|i\rangle\langle j|)^T = |j\rangle\langle i|$ .  $(M_1 + M_2)^T = M_1^T + M_2^T$

In general:  $M = \sum_{i,j=0}^{d-1} m_{ij} |i\rangle\langle j| \Rightarrow M^T = \sum_{i,j=0}^{d-1} m_{ij} |j\rangle\langle i|$

$$M^T = \left( \sum_{i,j=0}^{d-1} m_{ij} |i\rangle\langle j| \right)^T = \sum_{i,j=0}^{d-1} m_{ij} (|i\rangle\langle j|)^T$$

\* A matrix  $M$  is called symmetric if  $M^T = M$ .

$$M^T = M \rightarrow m_{ij} = m_{ji}$$

## - Conjugate Transpose of a Matrix:

• Recall for vectors:  $|v\rangle = \begin{pmatrix} v_0 \\ v_1 \\ \vdots \\ v_{d-1} \end{pmatrix} \Rightarrow \langle v| = (\bar{v}_0 \ \bar{v}_1 \ \dots \ \bar{v}_{d-1})$   
OR:  $|v\rangle = \sum_{k=0}^{d-1} v_k |k\rangle \Rightarrow \langle v| = \sum_{k=0}^{d-1} \bar{v}_k \langle k|$

• Similar for matrices!  $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \Rightarrow M^\dagger = \begin{pmatrix} \bar{a} & \bar{c} \\ \bar{b} & \bar{d} \end{pmatrix}$  "dagger"

• In general:  $M = \sum_{i,j=0}^{d-1} m_{ij} |i\rangle\langle j| \Rightarrow M^\dagger = \sum_{i,j=0}^{d-1} \bar{m}_{ij} |j\rangle\langle i|$

⊛ Note:  $(|i\rangle\langle j|)^\dagger = |j\rangle\langle i|$

$$M = \begin{pmatrix} a & b \\ \bar{b} & d \end{pmatrix}, \bar{a}=a, \bar{d}=d \quad (a, d \in \mathbb{R})$$

$\rightarrow m_{ij} = \bar{m}_{j,i}$

⊛ A matrix  $M$  is called Hermitian if  $M^\dagger = M$ .

## - Inner Product and Orthonormal Bases of Matrices.

• Recall vector inner product:  $|u\rangle = \sum_{k=0}^{d-1} u_k |k\rangle, |v\rangle = \sum_{k=0}^{d-1} v_k |k\rangle$   
 $\Rightarrow \langle u|v\rangle = \left( \sum_{k=0}^{d-1} \bar{u}_k \langle k| \right) \left( \sum_{k=0}^{d-1} v_k |k\rangle \right) = \sum_{k=0}^{d-1} \bar{u}_k v_k$

• Matrix inner product:  $\langle M_1, M_2 \rangle = \text{Tr}[M_1^\dagger M_2], \langle M_2, M_1 \rangle = \overline{\langle M_1, M_2 \rangle}$

From this, we define a norm for matrices:  $\|M\|_2 = \sqrt{\langle M, M \rangle} = \sqrt{\text{Tr}[M^\dagger M]}$

• Matrices  $M_1, M_2$  are orthogonal if  $\langle M_1, M_2 \rangle = 0$ .

• We have bases for matrices as well!

$$\left( \begin{smallmatrix} 1 \\ 0 \\ 0 \end{smallmatrix} \right), \left( \begin{smallmatrix} 0 \\ 1 \\ 0 \end{smallmatrix} \right), \left( \begin{smallmatrix} 0 \\ 0 \\ 1 \end{smallmatrix} \right)$$

Example:  $d=2$ , recall  $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix} = a|0\rangle\langle 0| + b|0\rangle\langle 1| + c|1\rangle\langle 0| + d|1\rangle\langle 1|$ .

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

The set  $\{|0\rangle\langle 0|, |0\rangle\langle 1|, |1\rangle\langle 0|, |1\rangle\langle 1|\}$  is an orthonormal basis for  $L(\mathbb{C}^2)$ .

↳ Observe: there are  $4 = 2^2$  elements!  $\langle B_i, B_j \rangle = \delta_{ij}$

Check: take inner products!

$$\langle |0\rangle\langle 0|, |0\rangle\langle 1| \rangle = \text{Tr} \left[ (|0\rangle\langle 0|)^\dagger (|0\rangle\langle 1|) \right] = \text{Tr} \left[ |0\rangle\langle 0|0\rangle\langle 1| \right] = \text{Tr} \left[ |0\rangle\langle 1| \right] = \langle 1|0 \rangle = 0.$$

$$\langle |0\rangle\langle 1|, |1\rangle\langle 0| \rangle = \text{Tr} \left[ (|0\rangle\langle 1|)^\dagger (|1\rangle\langle 0|) \right] = \text{Tr} \left[ |1\rangle\langle 0|0\rangle\langle 1| \right] = 0.$$

$$\langle |0\rangle\langle 0|, |0\rangle\langle 0| \rangle = \text{Tr} \left[ (|0\rangle\langle 0|)^\dagger |0\rangle\langle 0| \right] = \text{Tr} \left[ |0\rangle\langle 0|0\rangle\langle 0| \right] = \text{Tr} \left[ |0\rangle\langle 0| \right] = \langle 0|0 \rangle = 1$$

In general:  $\langle |i\rangle\langle j|, |k\rangle\langle l| \rangle = \text{Tr} \left[ (|i\rangle\langle j|)^\dagger |k\rangle\langle l| \right] = \text{Tr} \left[ |j\rangle\langle i|k\rangle\langle l| \right]$

$$= \delta_{i,k} \text{Tr} \left[ |j\rangle\langle l| \right] = \delta_{i,k} \langle l|j \rangle = \delta_{i,k} \delta_{j,l}$$

\* Holds for arbitrary dimension!  $\{|i\rangle\langle j| : i, j \in \{0, 1, \dots, d-1\}\}$  is an orthonormal basis for  $L(\mathbb{C}^d)$ .

• Special basis for  $d=2$ : Pauli Matrices (aka Pauli gates).

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\text{Tr}[X] = \text{Tr}[Y] = \text{Tr}[Z] = 0$$

$$X^2 = \mathbb{1}, \quad Y^2 = \mathbb{1}, \quad Z^2 = \mathbb{1}.$$

↳ Bit-flip matrix:  $X|0\rangle = |1\rangle, X|1\rangle = |0\rangle$ .

$$\text{Tr}(X^\dagger X) = 2 = \text{Tr}(Y^\dagger Y) = \text{Tr}(Z^\dagger Z)$$

They are Hermitian:  $x^\dagger = x$ ,  $y^\dagger = y$ ,  $z^\dagger = z$ .

They are orthogonal:  $\langle x, y \rangle = 0$ ,  $\langle x, z \rangle = 0$ ,  $\langle z, y \rangle = 0$ .

$\{x, y, z\}$  forms orthogonal basis for  $L(\mathbb{C}^2)$ !

$$\text{Tr}(x^\dagger y) = \text{Tr} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \text{Tr} \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = 0$$

$\Rightarrow$  Any  $M \in L(\mathbb{C}^2)$  can be written as  $M = \frac{1}{2}(c_0 \mathbb{1} + c_1 x + c_2 y + c_3 z)$ .  
 $c_0, c_1, c_2, c_3 \in \mathbb{C}$ .

### ③ Quantum States as Density Matrices

- We have seen state vectors:

$$|\psi\rangle = \alpha|0\rangle + \beta|1\rangle, \quad \alpha, \beta \in \mathbb{C}, \quad |\alpha|^2 + |\beta|^2 = 1.$$

- Consider the matrix  $\rho = |\psi\rangle\langle\psi|$ .

It has the following properties:

(1)  $\rho = \rho^\dagger$  (Hermitian),

$$\begin{aligned} |\psi\rangle\langle\psi| &= (\alpha|0\rangle + \beta|1\rangle)(\bar{\alpha}\langle 0| + \bar{\beta}\langle 1|) \\ &= |\alpha|^2 |0\rangle\langle 0| + \alpha\bar{\beta} |0\rangle\langle 1| + \beta\bar{\alpha} |1\rangle\langle 0| + |\beta|^2 |1\rangle\langle 1| \end{aligned}$$

$$(M_1 + M_2)^\dagger = M_1^\dagger + M_2^\dagger$$

$$(|\psi\rangle\langle\psi|)^\dagger = |\alpha|^2 (|0\rangle\langle 0|)^\dagger + \underbrace{\alpha\bar{\beta}}_{= \bar{\alpha}\beta} (|0\rangle\langle 1|)^\dagger + \underbrace{\beta\bar{\alpha}}_{= \bar{\beta}\alpha} (|1\rangle\langle 0|)^\dagger + |\beta|^2 (|1\rangle\langle 1|)^\dagger$$

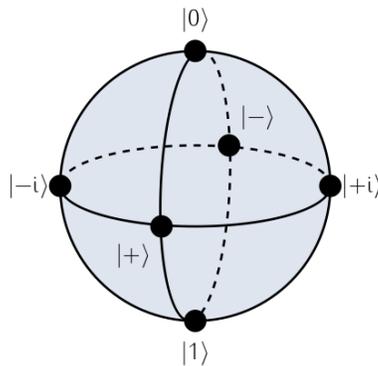
$$= \bar{\alpha}\beta = \bar{\alpha}\beta \quad = \bar{\beta}\alpha = \bar{\beta}\alpha$$

$$(\overline{z_1 \cdot z_2}) = \bar{z}_1 \cdot \bar{z}_2$$

$$\overline{\bar{z}} = z$$

$$= |\alpha|^2 |0\rangle\langle 0| + \bar{\alpha}\beta |1\rangle\langle 0| + \bar{\beta}\alpha |0\rangle\langle 1| + |\beta|^2 |1\rangle\langle 1|$$

$$= |\psi\rangle\langle\psi| \quad \checkmark$$



Qubit

$|0\rangle$  or  $|1\rangle$ ;  
or superposition

$$|\psi\rangle = \alpha|0\rangle + \beta|1\rangle,$$

$$\alpha, \beta \in \mathbb{C},$$

$$|\alpha|^2 + |\beta|^2 = 1$$

$$|\pm\rangle = \frac{1}{\sqrt{2}}(|0\rangle \pm |1\rangle)$$

$$|\pm i\rangle = \frac{1}{\sqrt{2}}(|0\rangle \pm i|1\rangle)$$

(2)  $\text{Tr}[\rho] = 1$  (unit trace).

$$\text{Tr}[\rho] = \langle \gamma | \rho | \gamma \rangle = |\alpha|^2 + |\beta|^2 = 1 \quad \checkmark$$

(from above!)

(3)  $\rho \geq 0$  (Positive Semi-definite).

(\*) A Hermitian matrix  $M \in L(\mathbb{C}^d)$  is called positive semi-definite (denoted  $M \geq 0$ ) if  $\langle v | M | v \rangle \geq 0 \quad \forall |v\rangle \in \mathbb{C}^d$ .

This is equivalent to: all eigenvalues are non-negative

(\*) Recall eigenvalues and eigenvectors:  $M|v\rangle = \lambda|v\rangle$ ,  $M = U \Lambda U^\dagger$ ,  $U^\dagger U = \mathbb{1}$ .  
diagonal matrix.  
Unitary  
Eigenvector  
Eigenvalue.

Eigenvalue (Spectral) decomposition:  $M = \sum_{k=1}^r \lambda_k |v_k\rangle\langle v_k|$

(\*) For  $\rho = |\gamma\rangle\langle\gamma| \rightarrow \langle v | \rho | v \rangle = \langle v | \gamma\rangle\langle\gamma | v \rangle = |\langle\gamma | v\rangle|^2 \geq 0 \quad \forall |v\rangle \checkmark$ .

- Any matrix satisfying (1), (2), (3) is called a density matrix/operator

(\*) Axiom of Quantum Mechanics: The state of any quantum system is mathematically by a density matrix. (arbitrary dimension).

- The density matrix  $\rho = |\gamma\rangle\langle\gamma|$  describes a pure state. (on the surface of the Bloch sphere.)

- What about more general density matrices? Consider  $d=2$ .

We can write  $\rho = \frac{1}{2}(c_0 \mathbb{1} + c_1 X + c_2 Y + c_3 Z)$  (b/c  $\{X, Y, Z\}$  is a basis).

We want this to satisfy: (1)  $\rho^\dagger = \rho$ ; (2)  $\text{Tr}(\rho) = 1$ ; (3)  $\rho \succ 0$ .

$$(1) \rho^\dagger = \frac{1}{2}(\bar{c}_0 \mathbb{1} + \bar{c}_1 X + \bar{c}_2 Y + \bar{c}_3 Z) \quad (X^\dagger = X, Y^\dagger = Y, Z^\dagger = Z)$$

$$\downarrow$$

$$= \frac{1}{2}(\bar{c}_0 \mathbb{1} + \bar{c}_1 X + \bar{c}_2 Y + \bar{c}_3 Z)$$

$$\stackrel{(!)}{=} \frac{1}{2}(c_0 \mathbb{1} + c_1 X + c_2 Y + c_3 Z) \Leftrightarrow c_0 = \bar{c}_0, c_1 = \bar{c}_1, c_2 = \bar{c}_2, c_3 = \bar{c}_3 \quad (\text{b/c } \{X, Y, Z\} \text{ is a basis})$$

(all are real numbers).

$$(2) \rho = \frac{1}{2}(r_0 \mathbb{1} + r_1 X + r_2 Y + r_3 Z), \quad r_0, r_1, r_2, r_3 \in \mathbb{R}.$$

$$\text{Tr}(\rho) = \frac{1}{2}(r_0 \underbrace{\text{Tr}(\mathbb{1})}_{=2} + r_1 \underbrace{\text{Tr}(X)}_{=0} + r_2 \underbrace{\text{Tr}(Y)}_{=0} + r_3 \underbrace{\text{Tr}(Z)}_{=0}) \stackrel{(!)}{=} 1 \Leftrightarrow \underline{\underline{r_0 = 1}}$$

$$(3) \rho = \frac{1}{2}(\mathbb{1} + r_1 X + r_2 Y + r_3 Z) \rightarrow \text{Find the eigenvalues!}$$

$$\begin{aligned} \textcircled{*} \text{ Observe: } \bullet \langle X, \rho \rangle &= \text{Tr}[X\rho] = \text{Tr}\left[X \cdot \frac{1}{2}(\mathbb{1} + r_1 X + r_2 Y + r_3 Z)\right] \\ &= \frac{1}{2}(\underbrace{\text{Tr}(X)}_{=0} + r_1 \underbrace{\text{Tr}(X^2)}_{=2} + r_2 \underbrace{\text{Tr}(XY)}_{=0} + r_3 \underbrace{\text{Tr}(XZ)}_{=0}) \\ &\downarrow \\ &= r_1 \end{aligned}$$

$$\bullet \langle Y, \rho \rangle = r_2$$

$$\bullet \langle Z, \rho \rangle = r_3.$$

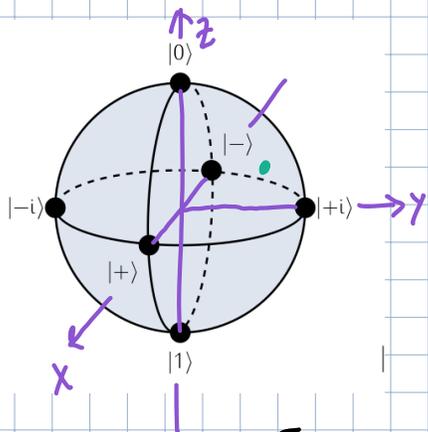
$$\rho = \frac{1}{2} \begin{pmatrix} 1+r_z & r_x - ir_y \\ r_x + ir_y & 1-r_z \end{pmatrix} \Rightarrow \lambda_{\pm} = \frac{1}{2} (1 \pm \sqrt{r_x^2 + r_y^2 + r_z^2}) \geq 0.$$

$$\text{Need } \lambda_- \geq 0 \Rightarrow \frac{1}{2} (1 - \sqrt{r_x^2 + r_y^2 + r_z^2}) \geq 0 \Rightarrow \underline{r_x^2 + r_y^2 + r_z^2 \leq 1}$$

$\vec{r} = (r_x, r_y, r_z) \in \mathbb{R}^3$  inside the unit sphere!

$$\text{Observe: } \|\rho\|_2^2 = \text{Tr}[\rho^2] = \frac{1}{2} (1 + \underbrace{r_x^2 + r_y^2 + r_z^2}_{\leq 1}) \leq 1$$

$$\rho = \frac{1}{2} (1 + r_x X + r_y Y + r_z Z)$$



$$\text{For a pure state } \rho = |\psi\rangle\langle\psi|, \rho^2 = |\psi\rangle\langle\psi| |\psi\rangle\langle\psi| = |\psi\rangle\langle\psi| \Rightarrow \text{Tr}[\rho^2] = 1$$

$$\Rightarrow r_x^2 + r_y^2 + r_z^2 = 1 \Rightarrow \text{pure states are on the surface of the unit sphere!}$$

\* We call  $\text{Tr}[\rho^2]$  the purity of  $\rho \rightarrow \rho$  pure if + only if  $\text{Tr}[\rho^2] = 1$ .

\* Origin,  $\vec{r} = (0,0,0)$  contains the maximally-mixed state:  $\frac{\mathbb{1}}{2}$ .

$$\frac{\mathbb{1}}{2} = \frac{1}{2} (|0\rangle\langle 0| + |1\rangle\langle 1|)$$

\* Points on the x-axis:  $\vec{r} = (\pm 1, 0, 0) \rightarrow \rho = \frac{1}{2} (\mathbb{1} \pm X) = |\pm\rangle\langle\pm|$ ,  $|\pm\rangle = \frac{1}{\sqrt{2}} (|0\rangle \pm |1\rangle)$   
 These are eigenstates of  $X$ :  $X|\pm\rangle = \pm|\pm\rangle$ .  
 $|\pm\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix}$

\* Points on the y-axis:  $\vec{r} = (0, \pm 1, 0) \rightarrow \rho = \frac{1}{2} (\mathbb{1} \pm Y) = |\pm i\rangle\langle\pm i|$ ,  
 $|\pm i\rangle = \frac{1}{\sqrt{2}} (|0\rangle \pm i|1\rangle) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm i \end{pmatrix}$   
 These are eigenstates of  $Y$ :  $Y|\pm i\rangle = \pm|\pm i\rangle$ .

\* Points on the z-axis:  $\vec{r} = (0, 0, \pm 1) \rightarrow \rho = \frac{1}{2} (\mathbb{1} \pm Z) \xrightarrow{(+)} |0\rangle\langle 0| \quad |0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$   
 $\xrightarrow{(-)} |1\rangle\langle 1| \quad |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$   
 These are eigenstates of  $Z$ :  $Z|0\rangle = |0\rangle$ ,  $Z|1\rangle = -|1\rangle$ .